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Math 1554 Linear Algebra Spring 2024

Midterm 3 (C) Make-up

PLEASE PRINT YOUR NAME CLEARLY IN ALL CAPITAL LETTERS

Name: Key GTID Number: _____

Student GT Email Address: _____@gatech.edu

Section Number (e.g. A3, G2, etc.) _____ TA Name _____

Circle your instructor:

Prof Barone Prof Belegradek Prof Kumar Prof Sun

Student Instructions

- **Show your work** and justify your answers for all questions unless stated otherwise.
- **Organize your work** in a reasonably neat and coherent way.
- **Simplify your answers** unless explicitly stated otherwise.
- **Fill in circles** completely. Do not use check marks, X's, or any other marks.
- Calculators, notes, cell phones, books are not allowed.
- Use dark and clear writing: your exam will be scanned into a digital system.
- Exam pages are double sided. Be sure to complete both sides.
- Leave a 1 inch border around the edges of exams.
- The last page is for scratch work. Please use it if you need extra space.
- This exam has 9 pages of questions.

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You do not need to justify your reasoning for questions on this page.

1. (a) (8 points) Suppose A is a real $m \times n$ matrix and $\vec{b} \in \mathbb{R}^m$ unless otherwise stated. Select **true** if the statement is true for all choices of A and \vec{b} . Otherwise, select **false**.

true false

- If A is an $n \times n$ real diagonalizable matrix, then A has n distinct eigenvalues.

e.g. $A = I$

- If $\text{proj}_{\vec{u}}(\vec{v}) = \vec{0}$, then $\{\vec{u}, \vec{v}\}$ is linearly independent.

e.g. $\vec{v} = \vec{0}$

- If $A = PDP^{-1}$ is diagonalizable and invertible, then A^{-1} is diagonalizable with the same matrix D .

$A^{-1} = P D^{-1} P^{-1}$ D^{-1} not D .

- If A has QR-factorization $A = QR$, then $\text{Nul}(A^T) = \text{Nul}(Q^T)$.

$\text{Nul } A^T = (\text{Col } A)^\perp = (\text{Col } Q)^\perp = \text{Nul } Q^T \checkmark$

- If $A\vec{x} = \vec{x}$ and $A\vec{y} = 2\vec{y}$ then the matrix $B = [\vec{x} \ \vec{y}]$ has rank 2.

$\{\vec{x}, \vec{y}\}$ linearly independent

- Every 4×4 real matrix A has a real eigenvalue.

$B = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ & $A = \begin{bmatrix} B & 0 \\ 0 & B \end{bmatrix}$

- If U is an $n \times n$ orthogonal matrix, then $UU^T = I_n$.

$U^T = U^{-1}$

- If A is $n \times n$ and A has n distinct real eigenvectors, then A is diagonalizable.

e.g. $A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$ $\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ 0 \end{bmatrix}, \dots$ are all eigenvectors w/ $\lambda = 1$

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(b) (4 points) Indicate whether the following situations are possible or impossible.

possible impossible

- | | | |
|----------------------------------|----------------------------------|---|
| <input checked="" type="radio"/> | <input type="radio"/> | A 2×2 matrix A such that A is an orthogonal matrix and $\det(A) = -1$.
e.g. $A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ |
| <input checked="" type="radio"/> | <input type="radio"/> | A 3×3 matrix in RREF that has exactly one pivot and is not diagonalizable.
e.g. $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ |
| <input type="radio"/> | <input checked="" type="radio"/> | A real 5×5 matrix A whose eigenvalues are precisely $i, 1, 1 + i, 1 - i, 0$.
$\bar{i} = -i$ must also be eigenvalue. |
| <input checked="" type="radio"/> | <input type="radio"/> | A real 5×5 matrix A with exactly two real eigenvalues, and the two eigenspaces of A have dimension 2 and dimension 3, respectively. |

e.g. $A = \begin{bmatrix} 2 & 0 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$

(c) (2 points) Which of the following are examples of a matrix A which satisfy the following property. The matrix A is not diagonalizable while the matrix A^2 is diagonalizable. Select all that apply.

- $\begin{pmatrix} 0 & -1 \\ 0 & 0 \end{pmatrix} \rightarrow A^2 = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$ diag'ble \checkmark but A has \checkmark
geo = 1 for $\lambda = 0$
alg = 2
so not diag'ble
- $\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \rightarrow \lambda_1 = 1, \lambda_2 = -1$ A diag'ble \times
- $\begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \rightarrow A$ not diag'ble, no real eigenvalues \checkmark
- $\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \rightarrow A^2 = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$ diag'ble \checkmark

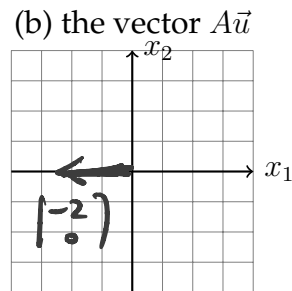
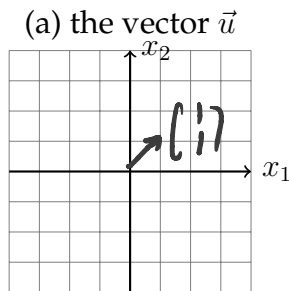
$\hookrightarrow \lambda_1 = 2, \lambda_2 = 0$ A diag'ble \times

$$\begin{pmatrix} -1 & -1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} -2 \\ 0 \end{pmatrix}$$

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2. (5 points) Consider $A = \begin{pmatrix} -1 & -1 \\ 1 & -1 \end{pmatrix}$, $\vec{u} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$. Sketch (a) the vector \vec{u} and (b) the vector $A\vec{u}$. Then, fill in the blanks for the following statements to make the statements true.



- (c) The transformation defined by $A = \begin{pmatrix} -1 & -1 \\ 1 & -1 \end{pmatrix}$ is a rotation-dilation where the rotation is through $\boxed{135^\circ}$ (degrees or radians counter-clockwise) and the scaling factor is $\boxed{\sqrt{2}}$.

- (d) An eigenvector associated to the eigenvalue $\lambda = -1+i$ of A is the vector $\vec{x} = \begin{pmatrix} \boxed{i} \\ 1 \end{pmatrix}$.
- $$A - \lambda I = \begin{bmatrix} -1 & -1 \\ 1 & -1 \end{bmatrix} - \begin{bmatrix} -1+i & 0 \\ 0 & -1+i \end{bmatrix} = \begin{bmatrix} -i & -1 \\ 1 & -i \end{bmatrix} \sim \begin{bmatrix} 1 & -i \\ 0 & 0 \end{bmatrix} \quad \vec{x} = s \begin{pmatrix} i \\ 1 \end{pmatrix}$$

3. (3 points) Fill in the blanks so that the following statements are true. Let $A = PDP^{-1}$ where

$$P = \begin{pmatrix} 2 & 2 & 3 \\ 1 & 1 & 3 \\ 2 & 1 & 1 \end{pmatrix} \quad D = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 3 \end{pmatrix}$$

- (a) An eigenvector of A corresponding to eigenvalue $\lambda = 4$ is $\vec{x} = \begin{pmatrix} \boxed{6} \\ 3 \\ \boxed{3} \end{pmatrix}$.

- (b) The vector $\vec{x} = \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix}$ is an eigenvector of A corresponding to eigenvalue $\lambda = \boxed{3}$.

- (c) The characteristic polynomial of A is equal to $\boxed{p(\lambda) = -(\lambda - 3)^2(\lambda - 4)}$.

You may leave your answer in factored form.

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 You do not need to justify your reasoning for questions on this page.

4. (6 points) Fill in the blanks.

(a) Suppose \vec{u} and \vec{v} are vectors in \mathbb{R}^n and that $\vec{u} \cdot \vec{v} = -4$, $\|\vec{u}\| = \sqrt{6}$ and $\|\vec{v}\| = 2\sqrt{2}$.
 Determine the length of $2\vec{u} - 3\vec{v}$.

$$\|2\vec{u} - 3\vec{v}\| = \boxed{12}$$

$$(2\vec{u} - 3\vec{v}) \cdot (2\vec{u} - 3\vec{v})$$

$$= 4\vec{u} \cdot \vec{u} - 12\vec{u} \cdot \vec{v} + 9\vec{v} \cdot \vec{v}$$

$$= 4(\sqrt{6})^2 - 12(-4) + 9(2\sqrt{2})^2$$

$$= 4 \cdot 6 + 48 + 9 \cdot 8 = 24 + 48 + 72 = 144$$

$$\text{So } \|2\vec{u} - 3\vec{v}\| = \sqrt{(2\vec{u} - 3\vec{v}) \cdot (2\vec{u} - 3\vec{v})}$$

$$= \sqrt{144} = \underline{\underline{12}}$$

(b) A 3×2 matrix such that $\text{Col}(A)^\perp$ is spanned by $\begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$.

$$A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \\ 0 & -1 \end{pmatrix}$$

needs to have
 2 pivots and
 all columns
 orthogonal to
 $\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$.

(c) Write $\vec{y} = \vec{x} + \vec{z}$ as the sum of two vectors, where \vec{x} in $\text{span}\{\vec{u}\}$ and \vec{z} is orthogonal to \vec{u} .

$$\vec{y} = \begin{pmatrix} 5 \\ 3 \end{pmatrix} \quad \vec{u} = \begin{pmatrix} -1 \\ 1 \end{pmatrix} \quad \vec{x} = \begin{pmatrix} 1 \\ -1 \end{pmatrix} \quad \vec{z} = \begin{pmatrix} 4 \\ 4 \end{pmatrix}$$

$$\vec{x} = \text{Proj}_{\vec{u}}(\vec{y}) = \frac{\vec{y} \cdot \vec{u}}{\vec{u} \cdot \vec{u}} \vec{u} = \frac{-5+3}{2} \begin{bmatrix} -1 \\ 1 \end{bmatrix} = -\begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\vec{z} = \vec{y} - \vec{x} = \begin{bmatrix} 5 \\ 3 \end{bmatrix} - \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 4 \\ 4 \end{bmatrix}$$

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5. (4 points) Let W be the subspace in \mathbb{R}^4 which is the set of solutions to the following homogeneous linear equation. Find $\dim W$ and an orthonormal basis for W^\perp .

$$x_1 - x_2 + x_3 - 3x_4 = 0$$

$W = \text{Nul } A$ where

$$A = \begin{bmatrix} 1 & -1 & 1 & -3 \end{bmatrix}$$

$$\dim W = \boxed{3}$$

orthonormal basis for W^\perp is

$$\left\{ \frac{1}{\sqrt{12}} \begin{bmatrix} 1 \\ -1 \\ 1 \\ -3 \end{bmatrix} \right\}$$

$$W^\perp = (\text{Nul } A)^\perp = \text{Row } A = \text{span} \left\{ \begin{bmatrix} 1 \\ -1 \\ 1 \\ -3 \end{bmatrix} \right\}$$

So an orthonormal basis for W^\perp is

$$\frac{1}{\|\vec{v}\|} \vec{v} = \frac{1}{\sqrt{1+1+1+9}} \begin{bmatrix} 1 \\ -1 \\ 1 \\ -3 \end{bmatrix} = \frac{1}{\sqrt{12}} \begin{bmatrix} 1 \\ -1 \\ 1 \\ -3 \end{bmatrix}$$

$$\sqrt{12} = 2\sqrt{3}$$

Since $W = \text{Nul } A$ and $\text{rank}(A) = 1$ & # free vars is 3,
 $\dim W = 3$.

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6. (4 points) The matrix A has the QR factorization $A = QR$. Find the least-squares solution of the linear system $A\vec{x} = \vec{b}$ when

$$Q = \frac{1}{13} \begin{pmatrix} 5 & 12 \\ 0 & 0 \\ -12 & 5 \end{pmatrix}, \quad R = \begin{pmatrix} 1 & -2 \\ 0 & 3 \end{pmatrix}, \quad \vec{b} = \begin{pmatrix} 5 \\ 3 \\ 1 \end{pmatrix}.$$

$$A = QR \quad \text{and} \quad Q^T Q = I.$$

$$\hat{x} = \begin{bmatrix} 13/3 \\ 5/3 \end{bmatrix}$$

Normal equations

$$A^T A \hat{x} = A^T \vec{b} \quad \text{becomes}$$

$$(QR)^T QR \hat{x} = (QR)^T \vec{b}$$

$$\Rightarrow R^T Q^T QR \hat{x} = R^T Q^T \vec{b}$$

$$\Rightarrow \boxed{R \hat{x} = Q^T \vec{b}} \leftarrow \text{Solve this.}$$

$$\begin{aligned} Q^T \vec{b} &= \frac{1}{13} \begin{bmatrix} 5 & 0 & -12 \\ 12 & 0 & 5 \end{bmatrix} \begin{bmatrix} 5 \\ 3 \\ 1 \end{bmatrix} \\ &= \frac{1}{13} \begin{bmatrix} 13 \\ 65 \end{bmatrix} = \begin{bmatrix} 1 \\ 5 \end{bmatrix} \end{aligned}$$

$$\left[\begin{array}{cc|c} 1 & -2 & 1 \\ 0 & 3 & 5 \end{array} \right] \sim \left[\begin{array}{cc|c} 1 & -2 & 1 \\ 0 & 1 & 5/3 \end{array} \right] \sim \left[\begin{array}{cc|c} 1 & 0 & 13/3 \\ 0 & 1 & 5/3 \end{array} \right]$$

Ans.

$$\hat{x} = \begin{bmatrix} 13/3 \\ 5/3 \end{bmatrix}$$

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7. (4 points) Set $A = \begin{pmatrix} 0 & 0 \\ 2 & 3 \\ 4 & 6 \end{pmatrix}$. Find a basis for each of the four fundamental subspaces $\text{Col}(A)$, $\text{Nul}(A)$, $\text{Row}(A)$ and $\text{Nul}(A^T)$.

① $\text{Col } A = \text{span} \left\{ \begin{pmatrix} 0 \\ 2 \\ 4 \end{pmatrix}, \begin{pmatrix} 0 \\ 3 \\ 6 \end{pmatrix} \right\} = \text{span} \left\{ \begin{pmatrix} 0 \\ 2 \\ 4 \end{pmatrix} \right\}$ basis for $\text{Col}(A)$ is

$$\left\{ \begin{pmatrix} 0 \\ 2 \\ 4 \end{pmatrix} \right\}$$

② $\text{Nul } A \quad A \sim \begin{pmatrix} 1 & 3/2 \\ 0 & 0 \\ 0 & 0 \end{pmatrix} \vec{x} = s \begin{pmatrix} -3/2 \\ 1 \end{pmatrix}$ basis for $\text{Nul}(A)$ is

$$\left\{ \begin{pmatrix} -3/2 \\ 1 \end{pmatrix} \right\}$$

③ $\text{Row } A = \text{span} \left\{ \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 3 \end{pmatrix}, \begin{pmatrix} 4 \\ 6 \end{pmatrix} \right\} = \text{span} \left\{ \begin{pmatrix} 2 \\ 3 \end{pmatrix} \right\}$ basis for $\text{Row}(A)$ is

$$\left\{ \begin{pmatrix} 2 \\ 3 \end{pmatrix} \right\}$$

④ $\text{Nul } A^T = (\text{Col } A)^\perp$

need two vectors which are linearly independent & orthogonal to $\begin{pmatrix} 0 \\ 2 \\ 4 \end{pmatrix}$

e.g. $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ & $\begin{pmatrix} 0 \\ -4 \\ 2 \end{pmatrix}$

basis for $\text{Nul}(A^T)$ is

$$\left\{ \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ -4 \\ 2 \end{pmatrix} \right\}$$

Check $v_1 \cdot v_2 = 0$?

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$$1 - 3 + 1 + 1 = 0 \checkmark$$

8. (5 points) Show all work for problems on this page.

Find the vector \vec{x} which is in W and closest to \vec{y} , where the subspace W is spanned by \vec{v}_1 and \vec{v}_2 . Then, compute the distance from \vec{y} to W .

$$\vec{y} = \begin{pmatrix} 3 \\ 3 \\ 0 \\ 3 \end{pmatrix}, \quad \vec{v}_1 = \begin{pmatrix} 1 \\ 3 \\ -1 \\ 1 \end{pmatrix}, \quad \vec{v}_2 = \begin{pmatrix} 3 \\ -1 \\ 1 \\ 1 \end{pmatrix}.$$

$$\vec{x} = \text{proj}_{\{\vec{v}_1, \vec{v}_2\}}(\vec{y})$$

$$= \frac{\vec{y} \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 + \frac{\vec{y} \cdot \vec{v}_2}{\vec{v}_2 \cdot \vec{v}_2} \vec{v}_2 = \frac{3+9+3}{1+9+1+1} \begin{pmatrix} 1 \\ 3 \\ -1 \\ 1 \end{pmatrix} + \frac{9-3+3}{9+1+1+1} \begin{pmatrix} 3 \\ -1 \\ 1 \\ 1 \end{pmatrix}$$

$$\vec{x} = \begin{pmatrix} 7/2 \\ 3 \\ -1/2 \\ 2 \end{pmatrix}$$

$$= \frac{15}{12} \begin{pmatrix} 1 \\ 3 \\ -1 \\ 1 \end{pmatrix} + \frac{9}{12} \begin{pmatrix} 3 \\ -1 \\ 1 \\ 1 \end{pmatrix} = \frac{5}{4} \begin{pmatrix} 1 \\ 3 \\ -1 \\ 1 \end{pmatrix} + \frac{3}{4} \begin{pmatrix} 3 \\ -1 \\ 1 \\ 1 \end{pmatrix}$$

$$\text{dist}(\vec{y}, W) = \sqrt{3/2}$$

$$= \begin{pmatrix} 14/4 \\ 12/4 \\ -2/4 \\ 8/4 \end{pmatrix} = \begin{pmatrix} 7/2 \\ 3 \\ -1/2 \\ 2 \end{pmatrix}$$

$$\text{dist}(\vec{y}, W) = \|\vec{y} - \vec{x}\| = \left\| \begin{pmatrix} 3 \\ 3 \\ 0 \\ 3 \end{pmatrix} - \begin{pmatrix} 7/2 \\ 3 \\ -1/2 \\ 2 \end{pmatrix} \right\|$$

$$= \left\| \begin{pmatrix} -1/2 \\ 0 \\ 1/2 \\ 1 \end{pmatrix} \right\| = \sqrt{\frac{1}{4} + \frac{1}{4} + 1} = \sqrt{3/2}$$

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9. (5 points) Show all work for problems on this page.

Compute the parameters α and β of the least-squares curve $y = \alpha x + \beta \cos(\frac{\pi x}{3})$ that best fits the data below.

x	-2	0	1
y	-1	0	2

model is

$$y = \alpha x + \beta \cos\left(\frac{\pi x}{3}\right)$$

$$\alpha = \boxed{5/7}$$

$$\beta = \boxed{2/7}$$

Plug in data.

$$\textcircled{a} (-2, -1) \quad -2\alpha + \beta \cos\left(-\frac{2\pi}{3}\right) = -1$$

$$\textcircled{b} (0, 0) \quad 0\alpha + \beta \cos(0) = 0$$

$$\textcircled{c} (1, 2) \quad \alpha + \beta \cos\left(\frac{\pi}{3}\right) = 2$$

$$A = \begin{pmatrix} -2 & -1/2 \\ 0 & 1 \\ 1 & 1/2 \end{pmatrix}$$

$$A^T A = \begin{pmatrix} -2 & 0 & 1 \\ -1/2 & 1 & 1/2 \end{pmatrix} \begin{pmatrix} -2 & -1/2 \\ 0 & 1 \\ 1 & 1/2 \end{pmatrix}$$

$$b = \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix}$$

$$= \begin{pmatrix} 5 & 3/2 \\ 3/2 & 3/2 \end{pmatrix}$$

next.

Solve $A^T A \hat{x} = A^T b$, so

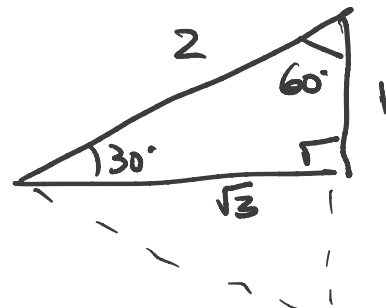
$$A^T b = \begin{pmatrix} -2 & 0 & 1 \\ -1/2 & 0 & 1/2 \end{pmatrix} \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix} = \begin{pmatrix} 4 \\ 3/2 \end{pmatrix}$$

$$\hat{x} = \begin{pmatrix} 5/7 \\ 2/7 \end{pmatrix}$$

reduce

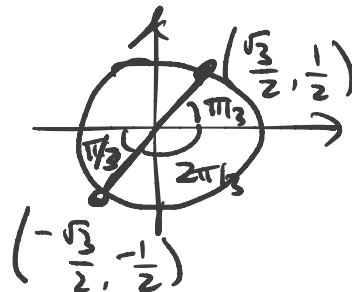
$$(A^T A | A^T b) = \left[\begin{array}{cc|c} 5 & 3/2 & 4 \\ 3/2 & 3/2 & 3/2 \end{array} \right] \sim \left[\begin{array}{cc|c} 1 & 1/2 & 1 \\ 5 & 3/2 & 4 \end{array} \right] \sim \left[\begin{array}{cc|c} 1 & 1/2 & 1 \\ 0 & -7/2 & -1 \end{array} \right]$$

$$\sim \left[\begin{array}{cc|c} 1 & 1/2 & 1 \\ 0 & 1 & 2/7 \end{array} \right] \sim \left[\begin{array}{cc|c} 1 & 0 & 5/7 \\ 0 & 1 & 2/7 \end{array} \right]$$



$$\cos(\pi/3) = 1/2$$

$$\cos(-2\pi/3) = -1/2$$



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